### VOLUME IV TEST MANAGEMENT PHASE

## CHAPTER 11 QUALITATIVE FLIGHT TESTING

DESTRIBUTION STATEMENT 8

Approved for public teleased

# 19970117 182

SEPTEMBER 1990

USAF TEST PILOT SCHOOL EDWARDS AFB CA

DTIC QUALITY INSPECTED 1

#### PURPOSE

Qualitative flight testing determines the maximum amount of information in the minimum amount of flying time in order to evaluate an aircraft with respect to its entire mission or some specific area of interest.

Qualitative flight testing has essentially the same purpose as quantitative flight testing, i.e., to determine how well the aircraft flies and how well it will perform its designed mission. To accurately evaluate an aircraft from quantitative data requires analysis of large amounts of precisely measured data. The best a pilot can hope to do on a qualitative evaluation is to measure a limited amount of quantitative data. Thus, the test pilot's opinion on the acceptability of the aircraft is the important result and measured quantitative data (when available) is used primarily to support this opinion. Quantitative values of stick forces measured with a hand gage, for example, should be included in the report to support the pilot's opinion of acceptability. Estimates of stick forces can be made if no reliable measurements are available or qualifying terms such as "heavy", "medium", or "light" can be used to describe the forces. The point is that the difference in evaluating an aircraft qualitatively and quantitatively is a matter of degree. "Use what you've got." Pilot opinion supported by measured data is primary in qualitative testing, while the reverse is true in quantitative testing. The general rule is to first decide how well the aircraft does its job and then use the quantitative data you can get to support your opinion.

#### PILOT OPINION

Naturally, all pilots will not have exactly the same opinion regarding the acceptability of a particular aircraft characteristic. No two people think exactly alike. However, the opinions of pilots with similar experience and background will usually not differ greatly, particularly with respect to the capability of an aircraft to perform a specific mission. In other respects, such as cockpit arrangements, the opinions may vary more markedly. For this reason, it is important for the qualitative test pilot to be as objective as possible in his evaluation. Guides which specify military requirements, such as MIL-STD-203F , should be used wherever possible to establish acceptability. However, mere compliance with a set of requirements does not necessarily yield a satisfactory aircraft. The primary question is "will it do the job?", not "does it meet the specifications?"

#### MISSION PREPARATION

A very limited amount of flight time is normally available for a qualitative evaluation. To acquire the information necessary to write an accurate and comprehensive report on an aircraft in this limited time requires a great deal of preflight study and planning.

The preflight preparation for a qualitative test is extremely important. It is almost impossible to put in too much time in planning for the flights. The amount of information acquired in the air will be directly proportional to the amount of preparation put in on the ground. A pilot who doesn't know what he is looking for is not likely to find it, and to know exactly what to look for in the evaluation requires considerable knowledge of the aircraft and its mission.

The precise mission of the aircraft is important in determining what specific investigations should be made in the evaluation. All fighters, for instance, do not have the same mission, and the characteristics of particular importance may not be the same. The roll characteristics of an air superiority fighter would be more important than for a long range strategic fighter, and the specific test plan should take this fact into account. Expected outstanding characteristics or weaknesses should also receive particular emphasis. Of course, the evaluation must be conducted within the cleared flight envelope of the aircraft, and the amount of flight time available may limit the number of altitudes, airspeeds, and tests that can be investigated. However, concentration on the extremes of altitudes, airspeeds, etc., and the areas dictated by the primary mission will provide the best approach to the test planning.

An outline of the test to be conducted and the various altitudes, airspeeds, and configurations to be used will aid in organizing the flights and planning the flight data cards. The points included in the outline should be compatible with the time available for the evaluation but it is always wise to overplan the flight and include more than seems possible to accomplish in the allotted time. Leave yourself the option of skipping the less important parts of your plan if time or fuel runs short. The sequence of tests should be such that as little time as possible is wasted. With proper planning a continuous flow from one investigation to the next is possible.

#### FLIGHT DATA CARDS

Before planning the flight data cards, as much as possible should be learned about the aircraft. Study the pilot's handbook if one is available, discuss the aircraft with the engineers, or with other pilots who have flown it, and get adequate cockpit time. The more the pilot knows about the aircraft and the more comfortable he is in it, the more thorough the evaluation will be. A pilot who doesn't know the aircraft procedures, both normal and emergency, or who has to spend most of his time in the air looking for controls or switches will not be able to do much evaluating.

The flight data cards should be self explanatory and should include all the points to be investigated during the flight. They should be designed so that a minimum of writing is required in the air because time will not be available to write down more than a word or two about each point. Remember, however, to provide places in the flight plan to write down these necessary comments. Numerous forms for the data cards are possible but completeness and legibility are essential.

Figures 1 through 4 present some possible formats and ideas for flight evaluation cards.

#### GENERAL TECHNIQUES

The cockpit evaluation can normally be made while getting cockpit time prior to the first flight. MIL-STD-203F specifies the standard cockpit arrangement for the various types of aircraft in considerable detail and should be used as a guide in making the cockpit evaluation. However, a summary of some of the points to note may prove helpful. These include ease of entry, comfort, adjustment of seat and controls, location of basic flight instruments, size and legibility of instruments, accessibility of switches and controls, ease of identification of switches and controls, location and identification of emergency switches and controls, methods of escape (both on the ground and airborne), and general impression of cockpit layout.

Several points should be observed and recorded during the start and while preparing the aircraft for flight. These should be weighed against the aircraft's mission requirements. An all-weather interceptor, for example, should be capable of fast, uncomplicated starts to meet its alert and scramble requirements. Starts for other types may not be so critical; however, no starting procedure should be unnecessarily complex or confusing. Evaluation of the start should include: complexity of start, time to prepare for start, time to start, external power and ground support equipment required, ground personnel required, and time from start to taxi. The system checks and normal procedure requirements from start to taxi should also be evaluated.

An evaluation of the ground handling characteristics can be made while taxiing. How much power is required to start moving and to taxi at the desired speed? Is braking action required to prevent taxiing too fast? Is the visibility adequate? Is the directional control satisfactory? Is the braking action satisfactory? What is the turning radius of the aircraft? Does the aircraft require any auxiliary equipment such as removable wheels, escape ladders, etc? Is there any problem with clearing obstacles with any part of the aircraft?

The takeoff distance may be difficult to determine without assistance from outside personnel, but an estimate should be made using whatever aid is available such as runway distance markers. Use the recommended takeoff procedure; don't try to make a maximum performance takeoff. The normal ground roll will be of more interest than the minimum possible. Some of the other

points to note in the takeoff include: ability of brakes to hold in military power, directional control during ground roll, rudder effective speed, nose lift-off speed, visibility after nose up and during initial acceleration and climb, force required to raise nose, any over-controlling tendencies, airborne speed, adequacy of recommended takeoff trim settings, time to retract gear and flaps, trim changes with retraction of gear and flaps, any tendency to exceed gear or flap speed limitations, effectiveness of trimming action during acceleration, and any distracting noises or vibrations.

The in-flight techniques differ very little from the techniques used in flying quantitative tests. However, it generally is not necessary to be as precise in holding airspeeds and altitudes. To do so would only waste time because differences caused by variations of a few hundred feet in altitude or a few knots in airspeed will not be qualitatively discernible. This is not an endorsement for being lax in flying the aircraft. Just don't waste time with precision that will not contribute to the evaluation of the aircraft. If speeds are critical, such as in the climb or in the pattern, then maintain them as closely as possible. Otherwise, use good judgment in determining how close to an aim condition it is necessary to be and fly accordingly.

If the climb rate of the aircraft is relatively slow, it may be possible to get some stability information in the climb, i.e., stick pulses, sideslips, etc. Most present day fighter aircraft climb so rapidly that this may not be practical. If so, just record climb performance data (time, fuel, and indicated speed) at intervals of approximately 5,000 feet. Start the time at brake release. Intercept the climb schedule at a comfortable altitude and attempt to fly the recommended schedule precisely. Continue the climb only as far as necessary to meet the objective of the flight. Unless climb performance is of primary importance, this will probably be to the altitude selected for the first series of investigations. General aircraft characteristics should be observed during the climb. How difficult is it to maintain the recommended climb schedule? Are the control responses smooth, too fast, too Is visibility adequate? Is there any buffet, vibration or excessive slow? noise? Are the ventilation and pressurization systems satisfactory? Are the normal procedures complicated or excessively distracting? If dampers or other artificial stability devices are provided, check the applicable characteristics with them ON and OFF.

The altitude selected for the first series of stability investigations may be at the tropopause since this is where the aircraft will probably have its best performance. However, if the designed operating altitude is considerably higher it may be advisable to select an altitude at or near the aircraft's operating altitude. The stability maneuvers performed will be essentially the same at all the altitudes and airspeeds selected. These should be sufficiently spaced to assure discernible qualitative differences in the aircraft's characteristics.

The stability characteristics investigated should include longitudinal and directional static stability, longitudinal and directional dynamic stability, aileron rolls, and maneuvering flight at several different airspeeds and altitudes. An investigation of the transonic trim changes also should be made. All the dynamic characteristics should be checked with the stability augmentation devices, if any, both ON and OFF. With proper planning these investigations can be made in a minimum amount of time. The longitudinal static stability can be checked while accelerating to  $V_{max}$ , for instance. Once at  $V_{max}$ , the aircraft can be trimmed for approximately hands-off flight and the static directional stability checked by entering a steady sideslip out to maximum rudder deflection (if the aircraft is cleared to that limit). The periods of the dynamic modes can be timed using a stop watch or counting the Estimate the number of the cycles to damp completely or to one-half seconds. amplitude, as the case may be, for all the modes.

Approach the aileron rolls cautiously. Make several partial deflection rolls before making any full deflection rolls. The time to reach  $90^{\circ}$  of roll and the time to roll  $360^{\circ}$  can be estimated using a stopwatch or again by counting the seconds. It is advisable to make rapid reversals of ailerons and other rolling maneuvers if these can be expected in operational use of the aircraft. The rolling characteristics should also be checked in accelerated flight as well as lg flight.

After completion of investigations at  $V_{max}$ , a windup turn to limit load factor can be made to check the maneuvering stability of the aircraft. Then zoom back to the original altitude and repeat these investigations at the second airspeed. The other altitudes and airspeeds can be checked in the same

manner. Any differences resulting from altitude or speed changes should be noted.

If the aircraft is cleared for stalls, they should be investigated cautiously in all configurations and types of entry. Determine the approximate stall warning margin, what defines the warning and the stall, and the aircraft characteristics in the stall and the recovery. If possible, determine the best method of breaking the stall and altitude loss in recovery from several points in the stall.

If possible, check the tactical mission capability of the aircraft. Simulated dive bombing runs or LABS maneuvers could be made for a tactical fighter for example. All the information obtainable will be helpful in writing an accurate and comprehensive report.

Fly the traffic pattern as recommended and, if fuel permits, make a go-around on the first pass. Note the power response, power required in the pattern, airspeed control and sink rate, trim changes with gear and flap extension, trimming action, buffet with gear extension, and general aircraft feel in the pattern. On the go-around, recheck the trim changes with gear and flap retraction and with drag device reaction. Don't forget to look at engine out characteristics if time and fuel permit. On the first landing in the aircraft it is probably not advisable to attempt to get the minimum landing roll. Make a normal touchdown and use normal braking action (use the drag chute if provided). Note the touchdown speed, the effects of any crosswind, directional control, nose lowering speed, etc. As with the takeoff, the normal landing roll is of more importance than the minimum possible.

Review the flight while taxiing back to the parking area. Re-evaluate the cockpit, and attempt to determine whether the aircraft will perform its design mission and is safe and comfortable to fly. Your opinion with everything fresh in mind is probably the most accurate. Put everything you remember about the flight and your impressions of the aircraft down on paper immediately after leaving the aircraft. Do this immediately and before talking to anyone about the airplane or the flight. Waiting or discussing points with other people may alter first hand impressions or cause important aspects of the flight to be forgotten.

#### INITIAL FLIGHT REPORT

The test pilot's ability to qualitatively evaluate an aircraft in limited flying time is only part of the evaluation. His ability to communicate his finding is an extremely important step that must not be neglected. An "Initial Flight Report" should be written as soon as possible after the flight. At the Flight Test Center this is accomplished on the AFSC FORM 5314.

The report should express everything learned about the aircraft. A narrative form is normally used for qualitative reports. Comparisons with other aircraft can be used to assist in describing the aircraft. Take care to ensure that only aircraft familiar to most readers are used for comparison. Otherwise the comparison will mean nothing to them.

Keep in mind the purpose of the qualitative evaluation while writing the report. Mere figures are normally not enough to describe the stability of the aircraft, particularly on a qualitative evaluation since the data obtained are very limited. Analyze the aircraft's characteristics in light of its ability to perform its design mission, give opinions of the aircraft's ability to do the job and support these opinions with the facts obtained on the evaluation flights. Comment on anything personally disliked but be objective in condemning any shortcomings. Recommendations for specific changes in the aircraft are to be included in the report. The exact manner in which the aircraft should be fixed should not be specified or recommended. The test pilot's job is to evaluate the existing hardware and state what should be changed. It is then the manufacturer's responsibility to determine how to make the necessary changes.

#### QUALITATIVE EVALUATION PREPARATION CHECKLIST

1. Identify the mission in detail. (Is this newly proposed tasking, or related tasking but by a new user?) 2. Determine a typical and complete mission profile. ( A full list of all mission tasks) Generic tasks Primary mission tasks Mission flight conditions Ancillary mission tasks 3. Accomplish a Detailed Task Analysis. (Don't slight this) 4. Research the aircraft thoroughly. 5. Build an evaluation profile. Sortie length Weather Open loop "feel" of the aircraft Start at the heart of the envelope Mission tasks Mission simulation tasks Comparison tasks Similar mission aircraft Aircraft you are familiar with Edges of the envelope Problem exploration - open loop 6. Assemble / construct the data cards Leave room to write Sliding scales work greatly Familiar cards are easier to use 7. Fly the evaluation. 8. Immediately complete an initial flight report (AFSC form 5314?) Do this before talking to anyone Don't get distracted or have your mind cluttered Write it to yourself 9. Write / present a detailed Qual Eval report Can it do the proposed mission?

. .

COCKPIT LAYOUT (INITIAL IMPRESSIONS, LOGICAL, COMFORT, CONTROLS, RUDD с. G. с.б. START UP (CHECK SEQUENCE, COMPLICATIONS, ETC.) COLL TURB P.HT с. w. G.W. CYC(LAT) 2 VIEW, WARNING/EMERG. SYSTEMS) PREFLIGHT (EASE/TIME TAKEN) DNIM MECHANICAL CHARACTERISTICS OAT FUEL FUEL CYC (LONG) LAND TIME T/O TIME F/GRADIENT DYNAMICS TRIM WEATHER FREEPLAY FRICTION B'OUT AIRCRAFT DESCRIPTION HELICOPTER FLIGHT CONT. DESC. COVERNING SYSTEMS STAB AUG SYSTEMS AIRFRAME/MISC ROTOR SYSTEM EMPTY WEIGHT MISSIONS MAX G.W. ENGINES MAX SHP SYSTEMS TYPE

APPENDIX B. Helicopter Qualitative Evaluation Cards

B.1

• ••	:	a second de la companya de la compa	and a subscription of the second	
LELATED TASKS	it on way to operating area, as possible, to determine F.Q. problem areas).			
SSION R	tential			
X				
-	ROTOR ENGAGEMENT (EASE, VIBRATION, ETC.) PRE TAKE-OFF DRILLS	ROUND HANDLING AXI (EASE) RAKES (EFFECTIVENESS) URNING RADIUS ERTICAL LIFT OFF FRITICAL LIFT OFF CE HOVER (QUAL: EVAL) NTO WIND MIND MIND MIND MIND	OWN WIND OWN WIND HQR GE HOVER T <sub>q</sub> N <sub>r</sub> FUEL HQR RANSITION (QUAL EVAL)	AX POWER - LIMIT IAS HQR HQR FUEL 1AS V FUEL 33

ų

в.2

•	MAN. STAB BANK ANGLE 'G & LONG & LONG FORCE			REMARKS	CONTROL RESPONSE	INPUT SENS EFFECT TIME (S/STATE)				REMARKS	LAT/DIR	STATIC STAB (CARRY JUT TOIC & SHSS)	Dihedral Eitect	Sideforces	DYNAMICS	SPIRAL STAB CHARACTER TIME CONST	DUTCH ROLL	Period	Roll/Yaw	Damping	LAT CYC CONT RESPONSE	6		
			•		-				<del>.</del>			· · ·		 -					• •	· · · ·				
	ß. and	REMARKS					2 2 2		۸V											U				
	attitudes/ 1 movements y)	RUDD							- - -											DAMP I N				
	controls & y of contro Frimmabilit	COLL					irspeed)		∇+ ₩											0'SHOOTS			S	
-	irtions (All of linearit; margins. <sup>1</sup>	LAT					QUALITIES relevant a.	= =	TRI			sce								TIME				
	LIGHT CONDI mpression o of control	5NOT					NAL FLYING or mission	ABILITY			CYCL.IC POS	CONTROL FOF	RESPONSE						M RESPONSE	CTER				
	FRIMMED F Seneral in adequacy	IAS					JONGI TUDI	· cruise STATIC ST.		TAS	TONG	DNOT	LONG TERM						SHORT TER	CHARA				

в.3

-	 	
MAX IAS (QUAL EVAL)		VERTICAL CLIMB (Max Power) Control movements
MAX		۷ .
V <sub>NE</sub>		FUEL WIND REMARKS
AUTO F.Q. VMIN SINK VV		CRITICAL AZIMUTH REL. WIND LIMITATION TURN ON SPOT (Qual Eval)
DECRADED MODES (STAB AUC/HYD. OFF)		CONTROL RESPONSE (LONG/LAT/YAW) INPUT SENS EFFECT TIME (S/STATE)
STAB AUG ASST		
MODE OPERATION		
	· .	REMARKS
	•	DYNAMICS (LONG/LAT Pure Motions)
LOW A/S F.Q.		
TRIMMED FLIGHT CONDITIONS	•	
SIDEWARD (L) LIMIT PARAMETER		
REARWARD LIMIT PARAMETER	•	
REMARKS 7		σ

в.4



#### THIS PAGE INTENTIONALLY BLANK

Å

.

G	IUAL EVALUATION			AIRCRAFT		
D	DATE LOC					
С	ONFIGURATION					
C	ALL SIGN	OPS :	#	_ TAIL #	ŧ	
G	i.W	CG%	FUEL LOAD_			GAL/LBS
	IMPORTANT MISSION	LIMITATIONS		RSPEED		
		=				
		<u> </u>	$- MAX G (5) \\ MAX C (5)$		WI	
te					WI	
St			- MAXG(S)		WI	
L					WI	
ច្ឆ			MAX G (A)		WI	· · · ·
		· · · · · · · · · · · · · · · · · · ·		170		
		)		115		
	DEE LIMITS	+				
	EGT	 	- DOM			MAX
	FF	 +	_ RPM	%0 。		%
	HYD					
	PNEU					
	TOBOUE					
	NOZ/TOP/TIT					
	MAX CANOPY SPEED					
	MAX NGS SPEED		AOA		ΔΟΔ	
				MTRS	+	
	MAX TAXI SPEED		CG LIMITS %		<u>то</u>	
	LINE UP CHECK		STORE LIMIT	rs		
	RPM	_ <u>+</u>	AIRSPE	ED		
	EGT	_±	GLIMIT		S	Α
	FF	_+	JETTIS	DN		
	OIL P	_ <u>+</u>	_ ZERO G. LIM	ITS		
	OIL QTY	_±				
		<u> </u>	_ NEGATIVE G	. LIMIT		
	NOZZLE		PROHIBITED	MANEUVERS		
	TOP/TIT		1			
	GEAR LIMIT SPEED		2			
	FLAP SCHED	1	3			
		2	4			
	FLAP LIMIT SPEED		NG LIFT OFF			
	EJECTION ENVELOPE	/BANK	MAIN GEAR	Т/О		
	AS/ALT	_ BK	_			
	AS/ALT	_ BK	<b>_</b>			
	AS/ALT	BK				



,

FIGURE 1. TYPICAL AIRCRAFT QUALITATIVE EVALUATION FLIGHT CARD COVER PAGE

.

.

MAX AIR MIL •• OTHERS XWINDS STORES AOA RUN UP 3 LOAD FACTOR GND ৬ NEG G 26RO G LIMITATIONS . ASYM γγ 574 RT PROHIBITED MANEUVERS GENERAL NOTES: STARTING NOTES: IMPOETANT ToRquE בקד/דויד NOZZ LE ENGINE : OILP Г Г CANOPY RPM SPEEDS FLAPS GEAR VMAX MACH f PA CA & DS COVER JOKER BING0 saunu FRZ LVL VALID TIME 11/1 10D TEMP 3 ¥290 <!> HES FOB WIND ALDFT (DIR/VEL/TEMP) OUNL EVALUTION sκγ ٠ · CG 30 - 25 З<u></u> 4 0 ていしょう ひつしんかつ SIGN フロドボリクコ WEATHER: オミンショナ . 11 トセン Fuel: CALL ENER HEAN MIN 0 . М. 20 Š เก

**C**-3

. . • 

. . . .



#### A. Support Equipment

- 1. Power Unit
  - Type Capacity
- 2. Other
- 2. 000

B. Cargo Compartment

- 1. Entrance
- 2. Egress
- 3. Systems Accessibility
- 4. Other
- C. Flight Deck
  - 1. Crew Stations
    - a. Pilot Seat Adjustment Clearance Vision Rudder Pedal Adjustment Restrictions Other
    - b. Copilot
    - c. Flight Mechanic
    - d. Navigator
  - 2. Instrument Panel
    - a. Flight Instruments Grouping Readability Adequacy
    - b. Engine Instruments Grouping Readability Adequacy
    - c. Warning Lights Placards Switches Controls
  - 3. Pedestal
    - a. Engine Controls System Controls Switches Guards Placards Lights Feel Identification Accessibility Confusion Factor Arrangement

- 4. Overhead Panel
  - a. Engine Controls System Controls Switches Guards Lights Placards Accessibility Feel Identification Confusion Factor Arrangement
  - b. Remarks
- 5. Side Panels a. Switches CBs Lights
  - b. Remarks
- 6. Flight Controls a. Rudder Break-out Force Travel Adjustment Clearance Slop Friction
  - b. Elevator Break-out Force Travel Slop Friction Clearance
  - c. Control Wheel Aileron Break-out Force Travel Slop Friction Clearance Grip Switches

7. General Comments

b. Remarks



5.	Vit	bration					
	а.	Noise					
	b.	Air vent deflect	tors				
	c.	Ventilation/hea	ating				
6.	Co	ontrol Required	To Maintain Pro	per Taxi Speed			
7.	Re	emarks:					
Pre-	Tal	ke-Off (line up a	t even 1,000 fe	et and check W/V			
1.	FII	ight Control Che	eck With Boost (	Operating			
	a.	b/o force					
	b.	rate					
	c.	deflection					
	d.	, slop					
	e.	friction					
2.	Fla	aps Set		Trim Set			
З.	Er	ngine Power Che	eck				
	a.	Acceleration					
		ldle	to		_ (MRP)	Sec.	
		Asymmetric					
		Overshoot					
	ь.	. Stabilized con	ditions: OAT				
		Eng	<u>% RPM</u>	Torque	TIT	<u>Throttle Pos</u>	
		1		····			
		2				<u></u>	
		3					
		4					
		nation Mald At M	IL PWR				
4.	Bi	rakes hold Al M					
4. 5.	Bi Fi	uel reading		DS. W/V		Kts.	
4. 5. Tak 1. 2.	Bi Fi e-( Si Bi	off. (Use flight d tart Time Form I	iata on knee boa BRAKE RELEAS	IDS. W/V Brd) E TO START CLIN	лв	Kĭs.	
4. 5. Tak 1. 2. 3.	Bi Fi e-( Si B	Off. (Use flight d tart Time Form l irake Release Ac	lata on knee boa BRAKE RELEAS Stion ol. Rudder Effe	nds. w/v ard) E TO START CLIN ctive	1B kts.	KIS.	
4. 5. Tak 1. 2. 3. 4.	Bi Fi e-( Si B D E	Off. (Use flight d tart Time Form I irake Release Ac irectional Contr levator Effective	lata on knee boa BRAKE RELEAS ction rol. Rudder Effe a (nose wheel of	IDS. W/V Bard) EE TO START CLIN ctive If)	1B kts. kts.	Kĭs.	
4. 5. Tak 1. 2. 3. 4. 5.	Bi Fi Si Bi D E	Off. (Use flight d tart Time Form I irake Release Ac ilectional Contr llevator Effective lleran Control	lata on knee boa BRAKE RELEAS ction rol. Rudder Effe e (nose wheel of	IDS. W/V Bard) EE TO START CLIN ctive ff) kts.	1B kts. kts.	Kĭs.	
4. 5. Tak 1. 2. 3. 4. 5. 6.	Bi Fi Bi Bi E A	Off. (Use flight d tart Time Form I irake Release Ac directional Contr levator Effective lieron Control	lata on knee boa BRAKE RELEAS ction col. Rudder Effect e (nose wheel of	IDS. W/V BITC) IE TO START CLIM Ctive If() kts. t. Lift-Off Speed	1B kts. kts.	Kts.	Sec.
4. 5. 1. 2. 3. 4. 5. 6. 7.	Bi Fi Si B D E A T C	Off. (Use flight d tart Time Form I irake Release Ac ilevator Effective ileron Control 	lata on knee boa BRAKE RELEAS ction col. Rudder Effect e (nose wheel of	nds. w/v ard) E TO START CLIM ctive ff) kts. t. Lift-Off Speed Pitch	1B kts. kts. tts. Trir	Kts. kts. Time	Sec.
4. 5. Tak 1. 2. 3. 4. 5. 6. 7. 8.	Bi Fi Bi D Ei Ai T	Off. (Use flight d tart Time Form I trake Release Ac irectional Control levator Effective lieron Control 	lata on knee boa BRAKE RELEAS ction col. Rudder Effect e (nose wheel of ff Gear	nds. w/v ard) E TO START CLIM ctive f() kts. t. Lift-Off Speed Pitch	18 kts. kts. tts. Trir	Kts. kts. Time	Sec.
4. 5. Tak 1. 2. 3. 4. 5. 6. 7. 8.	Bi Fi Si Bi D E Ai T T	Off. (Use flight d tart Time Form I tarke Release Ac irectional Control ilevator Effective ileron Control 	lata on knee boa BRAKE RELEAS ction col. Rudder Effect e (nose wheel of ff Gear sec.	nds. w/v ard) E TO START CLIM ctive ff) ff) t. Lift-Off Speed Pitch	18 kts. kts. tts. Trir	Kts. kts. Time	S <del>O</del> C.
4. 5. Tak 1. 2. 3. 4. 5. 6. 7. 8.	Bi Fi Bi DEAT TTY	Off. (Use flight d tart Time Form I tarke Release Ac irectional Control ilevator Effective ileron Control 	lata on knee boa BRAKE RELEAS ction rol. Rudder Effect e (nose wheel of ff Gear sec.	nds. w/v ie TO START CLIM ctive ff) ff) tfs. t. Lift-Off Speed Pitch	1B kts. kts. tts. Trir	Kts.	Sec.
4. 5. 1. 2. 3. 4. 5. 6. 7. 8.	Bi Fi Bi DEAT T T	Off. (Use flight d tart Time Form I irake Release Ac irectional Control ilevator Effective ileron Control .O. Distance control Force irim-Out – Raise 'aw	lata on knee boa BRAKE RELEAS ol. Rudder Effer e (nose wheel of ff Gear sec.	IDS. W/V BIDS. W/V IE TO START CLIN Ctive If) [f] [f] kts. t. Lift-Off Speed _ Pitch	1B kts. kts. tts. Trir	Kts. kts. Time	S <del>O</del> C.
4. 5. Tal 1. 2. 3. 4. 5. 6. 7. 8. 9	Bi Fi BDEAT TTYTT	Off. (Use flight d tart Time Form I tarke Release Ac irectional Control ilevator Effective ileron Control  O. Distance control Force irim-Out – Raise Trim	lata on knee boa BRAKE RELEAS ol. Rudder Effect ol. Rudder Effect on (nose wheel of figure fill Gear sec.  Flaps	IDS. W/V BIDS. W/V IE TO START CLIN Ctive If) [f] kts. t. Lift-Off Speed _ Pitch	1B kts. kts. Trir	Kts.	S <del>O</del> C.
4. 5. Tak 1. 2. 3. 4. 5. 6. 7. 8. 9	Bi e-() BDEATCTTYTT	Off. (Use flight d tart Time Form I irake Release Ac irectional Control ilevator Effective ileron Control 	lata on knee boa BRAKE RELEAS ol. Rudder Effer e (nose wheel of fi Gear sec.  Flaps sec.	IDS. W/V BIDS. W/V IE TO START CLIN Ctive Iff) [ff] kts. t. Lift-Off Speed _ Pitch	1B kts. kts. Trir	Kts.	Sec.
4. 5. 1. 2. 3. 4. 5. 6. 7. 8. 9	Bree () SBDEATCTTYTTT	Off. (Use flight d tart Time Form I irake Release Ac irectional Control ilevator Effective ileron Control .O. Distance control Force ime ime frim-Out – Raise frim-Out – Raise	lata on knee boa BRAKE RELEAS ction ol. Rudder Effer e (nose wheel of 	IDS. W/V BIDS. W/V IE TO START CLIN Ctive Iff) kts. t. Lift-Off Speed _ Pitch	1B kts. kts. Trir	kts. Time	Sec.
4. 5. Tak 1. 2. 3. 4. 5. 6. 7. 8 9	BF CONSERVENTIAN CO	Off. (Use flight d tart Time Form I irake Release Ac irectional Control ilevator Effective ileron Control ileron Control control Force ine control Force irim-Out – Raise frim  frim frim frim Acceleration to M	lata on knee boa BRAKE RELEAS ction ol. Rudder Effer e (nose wheel of Gearfi Gearfi Flapssec. 	IDS. W/V BIDS. W/V IE TO START CLIN Ctive If) If) Kts. t. Lift-Off Speed Pitch ROL SPEED	1B kts. kts. Trir	Kts.	Sec.
4. 5. Tak 1. 2. 3. 4. 5. 8. 7. 8 9 9	BI Geole SB DEATCTTYTTAA	Off. (Use flight d tart Time Form I irake Release Ac irectional Control ilevator Effective ileron Control ileron Control control Force in Control Force irim-Out - Raise frim rim-Out - Raise frim Acceleration to M Acceleration to C	lata on knee boa BRAKE RELEAS ction ol. Rudder Effed e (nose wheel of Gearff Gearff Flapssec.  KINIMUM CONT Climb Speed (1,0	IDS. W/V BIDS. W/V IE TO START CLIN Ctive If) Mts. t. Lift-Off Speed Pitch ROL SPEED 000 ft)	1B kts. kts. Trir	Kts.	Sec.
4. 5. Tak 1. 2. 3. 4. 5. 6. 7. 8 9 10 11	BIDEATCTTYTTAAV	Off. (Use flight d tart Time Form I trake Release Ac directional Control levator Effective dileron Control 	lata on knee boa BRAKE RELEAS ction ol. Rudder Effed e (nose wheel of fl Gear sec.  Flaps sec.  KINIMUM CONT Climb Speed (1, ( ch Angle	IDS. W/V BIDS. W/V IE TO START CLIN Ctive If) Kts. t. Lift-Off Speed Pitch ROL SPEED 000 ft)	1B kts. kts. Trir	Kts.	Sec.

F. Climb (M N \_\_\_\_\_\_°, 90° to W/V). 1. Visibility \_\_\_\_\_\_ Pitch Angle \_\_\_\_\_ 2. Record: FUEL at START CLIMB \_\_\_\_\_

TIME	Hi	Vi	R/C	Ti	% RPM	TORQUE	ТРТ	Wf
	4M.							
	8M.							
	10M_							
	12M_							
	14M_							
	16M_							
	18M_							
	20M_							
	22M_							
	24M_							
	26M_				······			
	28M_							
	30M_							
	32M							



.

#### FUEL at LEVEL-OFF

3. Check Cabin Pressurization:

1	OM	
1	5M	

20M\_\_\_\_\_

25M\_\_\_\_\_

30M \_\_\_\_\_ Note any fluctuations or surges.

4. Cabin Heat Adequacy a. Nesi glass

#### 5. Remarks

G. Cruise

- 1. Vmax
  - a. Hi\_\_\_\_\_
  - b. Vi\_\_\_\_\_ c. OAT\_\_\_\_\_
  - d. Flt. Controls
  - e. RPM\_\_\_\_\_
  - f. Torque \_\_\_\_\_
  - g. TIT\_\_\_\_\_
  - h. Wf\_\_\_\_\_
  - I. FUEL\_\_\_\_\_

2. Dynamics (Hi\_\_\_\_\_\_ Vi\_\_\_\_\_ Vi\_\_\_\_\_) Note Control Position a. Phugoid \_\_\_Vi<sub>in</sub>\_\_\_\_\_V<sub>max</sub>\_\_\_\_\_ \_°\_\_\_\_\_\_Damping\_\_\_\_\_\_ \_\_\_\_\_cycls \_\_\_\_\_ \_ V<sub>mIn</sub> ----1. 11m\_\_\_\_\_ 2. Sec/cyc \_\_\_\_\_ 1. Trim \_\_\_ b. Porpoise Mode. input\_\_\_\_ \_\_\_\_\_ ampl. \_\_ c. Spiral stability 1. RTØ10°\_\_\_\_ \_°/\_ \_\_\_\_\_ sec. 2. LFT " " \_\_\_\_\_\_°/\_\_\_\_\_ sec. 3. Remarks: 

 1. RT sideslip s/c \_\_\_\_\_ Roll \_\_\_\_\_ Yaw \_\_\_\_\_

 Damping \_\_\_\_\_\_ (1) \_\_\_\_\_ (2) \_\_\_\_\_ (3) \_\_\_\_\_

 2. LFT sideslip s/c \_\_\_\_\_ Roll \_\_\_\_\_ Yaw \_\_\_\_\_\_

 Damping \_\_\_\_\_\_ (1) \_\_\_\_\_ (2) \_\_\_\_ (3)

 d. Dutch Roll 3. (1) Norm (2) Damper Off (3) Rudder Power Off. e. Short Period 1. Fixed (1.0g) Damping \_\_\_\_ 2. Fixed (-1.0g) Damping\_\_\_\_\_ 3. Free (1.0g) Damping \_\_\_\_\_\_ 4. Free (-1.0g) Damping \_\_\_\_\_ 5. Remarks: 
 Maximum Range Data

 a. Hi \_\_\_\_\_\_\_ Vi \_\_\_\_\_\_ Vi \_\_\_\_\_\_ OAT \_\_\_\_\_\_ FUEL \_\_\_\_

 b. RPM \_\_\_\_\_\_\_ TPT \_\_\_\_\_\_\_
 3. Maximum Range Data Wf \_\_\_\_ c. Remarks: 4. Systems Check: Hi \_\_\_\_\_\_ Vi \_\_\_\_\_
 a. Engine shut-down, No. \_\_\_\_\_\_
 1. Time to feather \_\_\_\_\_ Control force \_\_\_\_\_ 2. Procedure, etc: b. Engine restart 1. Time to Normal power \_\_\_\_\_\_ Surge \_\_\_\_\_ Trim \_\_\_\_\_ 2. Procedure, etc: c. Anti-icing/de-icing system 1. Full operation effect on engines \_\_\_\_\_ 2. Nesi glass Other 3. Remarks: d. GTU/ATM operation \_\_\_\_ e. Pressurization/heating\_\_\_\_\_ f. Other: 5. Emergency Descent, Hi \_\_\_\_ Vi\_\_\_\_\_\_ (Initial) a. Time from cruise to start descent \_\_\_\_ b. Procedure: G and F \_\_\_\_\_ Clean \_\_\_\_ Pressurization \_\_\_\_ c. Time \_\_\_\_\_ from CR to Hi \_\_\_\_\_ at Vi \_\_\_\_\_ d. Visibility \_\_\_\_\_ Pitch \_\_\_\_ Control \_\_\_\_\_ e. Remarks:

2. Speed Speed 3. Accele 10 20 30 40 50 60 70 80 V/S 4. Remark 5. Trrim Chang 1. Contro 2. Runaw 5 sec d 5. Sec d 5. Turning Per 1. 60° Ø, T 2. 45° Lft 3. 45° Rt - 7. 60° Ø, T 5. 45° Lft 6. 45° Rt - 7. 60° Ø, T 8. 45° Lft 9. 45° Rt - POWER 10. 45° Lft 11. 45° Rt - 10. 45° Lft 11. 45° Rt - POWER 10. 45° Lft 11. Rt Ø 10 2. Lft 10° 5. Phugoid (H Sideslips, T 1. Rt 2. Lft TRIM (f 3. Rt 4. Lft	/ Pwr Vi / Pwr Vi pration, (RESE     	P M 		T T P) Initial Vi T P) Initial Vi Build-up). FUL H H (FIX) Time for	IT IT FUEL Bud L DEFLECT Hi Ii 90°	OAT
Speed 3. Accele 10 20 30 40 50 60 70 80 V/S 4. Remark 5. Trim Chang 1. Contro 2. Runaw 5 sec d 5. Spec d 5. 45° Lft 3. 45° Rt - 7. 60° Ø, 7 5. 45° Lft 6. 45° Rt - 7. 60° Ø, 7 8. 45° Lft 9. 45° Rt - POWER 10. 45° Rt - POWER 10. 45° Rt - 10. 4	/Pwr Vi pration, (RESE    	RPM TTRIM), Time TTRIM), Time TIME Non	Tc Tc /10 kts (M /ces/gradie /iAil S. Cruise. (I Ail Vi Vi	nt Build-up). FUL H (FIX) Time for	FUEL FUEL L DEFLECT Hi Hi	
3. Accele 10 20 30 30 40 50 60 70 80 V/S 4. Remark 5. Contro 2. Runaw 5 sec c 1. Contro 2. Runaw 5 sec c 5. 45° Lft 3. 45° Rt- 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt- 7. 60° Ø, 1 8. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- 10. 45° Lft 11. 45° Rt- 10. 45° Lft 11. 45° Rt- 10. 45° Lft 11. 45° Rt- 10. 45° Lft 11. Rt Ø 10 2. Lft 10° 5. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft 7. RIM (I 3. Rt 4. Lft	ration, (RESE	Time for 90° Time for 90° Time for 90° Time for 90°		nt Build-up). FUL H H	FUEL FUEL L DEFLECT HI HI 90°	
10 20 30 40 50 60 70 80 V/S 4. Remark 5. Contro 2. Runaw 5 sec c 1. Contro 2. Runaw 5 sec c 5. 45° Lft 3. 45° Rt - 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt - 7. 60° Ø, 1 8. 45° Rt - 7. 60° Ø, 1 8. 45° Lft 11. 45° Rt - 10. 45° Lft 11. 45° Rt - 10. 45° Lft 11. A5° Rt - 10. 45° Lft 11. Rt Ø 10 2. Lft 10° 5. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft 1. Rt 3. Rt 4. Lft	- 45° Rt (FIX) 	hin. Control for v on y d Aileron Rolls Time for 90° Time for 90° Time for 90° Time for 90° Time for 90°	ces/gradie /iAil s. Cruise. (I Vmax Vi	nt Build-up). FUL H H	FUEL Rud L DEFLECT _ Hi Ii 90°	
20 20 30 30 40 50 60 70 80 70 4. Remark 5. Trim Chang 1. Contro 2. Runaw 5 sec d 5. 45° Lft 3. 45° Rt- 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Lft 11. 45° Rt- POWEF 10. 45° Lft 11. 45° Rt- 10. 45° Lft 11. 45° Rt- 10. 45° Lft 11. 45° Rt- 10. 45° Lft 11. 800 10. 2. Lft 100 2. Lft 100 2. Lft 100 3. Rt 1. Rt 1. Rt 4. Lft	ft/m ks: l boost off ay Trim: Elev delay (build-up formance an Fime 360° - 45° Rt (FIX) - 45° Rt (FIX) Fime 360° - 45° Rt (FIX) Fime 360° - 45° Rt (FIX) Fime 360° - 45° Rt (FIX)	hin. Control for V on v d Aileron Rolls Time for 90° Time for 90° Time for 90° Time for 90°	/iAil S. Cruise. (I Vmax Vi Vi	nt Build-up). FUL H H H	FUEL Rud L DEFLECT _ Hi Ii 90°	
20         30         40         50         60         70         80         V/S         4. Remark         0. Trim Change         1. Contro         2. Runaw         5 sec d         5. Turning Pei         1. 60° Ø, 1         2. 45° Lft         3. 45° Rt         4. 60° Ø, 1         5. 45° Lft         6. 45° Rt         7. 60° Ø, 1         8. 45° Lft         9. 45° Rt         POWEF         10. 45° Rt         9. 45° Rt         9. 00WEF         10. 80 (H         Sideslips, T         1. Rt Ø10         2. Lft 10°         9. Phugoid (H         Sideslips, T         1. Rt         2. Lft         3. Rt         4. Lft	ft/m ks: J boost off ay Trim: Elev delay (build-up formance an Time 360° - 45° Rt (FIX) - 45° Ltt (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt (FIX) - 45° Rt (FIX) - 45° Rt (FIX)	hin. Control for V on v v v on v	Ces/gradie /iAil s. Cruise. (I V <sub>max</sub> Vi Vi	nt Build-up). FUL H H H	FUEL Rud L DEFLECT _ Hi Ii 90°	
40 50 60 70 80 4. Remark 5. Trim Chang 1. Contro 2. Runaw 5 sec o 2. Runaw 5 sec o 2. Turning Pel 1. 60° Ø, 1 2. 45° Lft 3. 45° Rt- 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- 10. 45° Lft 11. 45° Rt- 10. 45° Lft 11. 45° Rt- 10. 2. Lft 10° 0. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft 7. RIM (f 3. Rt 4. Lft	ft/m ks: ges: Hi t boost off ay Trim: Elev delay (build-up formance an Fime 360° - 45° Rt (FIX) - 45° Ltt (FIX) Fime 360° - 45° Rt (FIX) Fime 360° - 45° Ltt (FIX) Fime 360° - 45° Rt (FIX)	hin. Control for V on v v v v v on v v v on v v on v v on v v on v v on v v on v v v on v v v on v v v v v v v v v v v v v	Ces/gradie /iAil s. Cruise. (I V <sub>max</sub> Vi Vi	nt Build-up). FUL H H H	FUEL Rud L DEFLECT _ Hi Ii 90°	
50 50 60 70 80 V/S 4. Remark 5. Trim Chang 1. Contro 2. Runaw 5 sec o 5. Turning Pel 1. 60° Ø, 1 2. 45° Lft 3. 45° Rt - 7. 60° Ø, 1 5. 45° Lft 6. 45° Rt - 7. 60° Ø, 1 8. 45° Lft 10. 45° Lft 11. 45° Rt - 10. 45° Lft 11. 45° Rt - 10. 2. Lft 10° 9. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft 7. RIM (I 3. Rt 4. Lft	ft/m ks: J boost off ay Trim: Elev delay (build-up formance an Fime 360° - 45° Rt (FIX) - 45° Ltt (FIX) Fime 360° - 45° Rt (FIX) Fime 360° - 45° Rt (FIX) Fime 360° - 45° Rt (FIX)	hin. Control for V on v	Ces/gradie /iAil s. Cruise. (I V <sub>max</sub> Vi Vi	nt Build-up). FUL H H H	FUEL Rud L DEFLECT Hi Ii 90°	
60 60 70 80 V/S 4. Remarl 5. Trim Chang 1. Contro 2. Runaw 5 sec d 5. Sec d 5. 45° Lft 3. 45° Rt - 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt - 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt - POWER 10. 45° Rt - POWER 10. 45° Rt - 10. 45° Rt - 11. 45° Rt - 10. 45° Rt - 10. 45° Rt - 10. 45° Lft 11. 45° Rt - 10. 45° Lft 11. Rt Ø 10 2. Lft 10° 9. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft TRIM (f 3. Rt 4. Lft	ft/m ks: l boost off ay Trim: Elev delay (build-up rformance an Time 360° - 45° Rt (FIX) - 45° Ltt (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt (FIX) - 45° Rt	hin. Control for V on v	Ces/gradie /iAil S. Cruise. (I V <sub>max</sub> Vi Vi	nt Build-up). FUL H H H	FUEL Rud L DEFLECT Hi Ii 90°	
000	ft/m ks: l boost off ay Trim: Elev delay (build-up rformance an Time 360° - 45° Rt (FIX) - 45° Rt (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt - 45° Rt	hin. Control for V on v	Ces/gradie /iAil s. Cruise. (I V <sub>max</sub> Vi Vi	nt Build-up). FUL H H H	FUEL Rud L DEFLECT Hi Ii 90°	
80 80 V/S 4. Remarl 5. Trim Chang 1. Contro 2. Runaw 5 sec 5. Turning Per 1. 60° Ø, 1 2. 45° Lft 3. 45° Rt- 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- POWER 10. 45° Lft 11. 45° Rt- 10. 45° Lft 11. 45° Rt- 10. 2. Lft 10° 9. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft 1. RIM (f 3. Rt 4. Lft	ft/m ks: l boost off ay Trim: Elev delay (build-up rformance an Time 360° - 45° Rt (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt (FIX) - 45° Rt - 45° Rt	hin. Control for V on v	Ces/gradie /iAil s. Cruise. (I V <sub>max</sub> Vi Vi	nt Build-up). FUL H H H	FUEL Rud L DEFLECT Hi Ii 90°	
<ul> <li>50</li> <li>V/S</li> <li>4. Remarl</li> <li>5. Trim Chang</li> <li>1. Contro</li> <li>2. Runaw</li> <li>5 sec de</li> <li>5 sec de</li> <li>1. 60° Ø, 1</li> <li>2. 45° Lft</li> <li>3. 45° Rt -</li> <li>4. 60° Ø, 1</li> <li>5. 45° Lft</li> <li>6. 45° Rt -</li> <li>7. 60° Ø, 1</li> <li>8. 45° Lft</li> <li>9. 45° Rt -</li> <li>9. 45° Rt -</li> <li>9. 45° Rt -</li> <li>9. 45° Rt -</li> <li>10. 45° Rt -</li> <li>11. 45° Rt -</li> <li>12. Lft 10°</li> <li>9. Phugoid (H</li> <li>5. Sideslips, T</li> <li>1. Rt</li> <li>2. Lft</li> <li>7. RIM (f</li> <li>3. Rt</li> <li>4. Lft</li> </ul>	ft/m ks: l boost off ay Trim: Elev delay (build-up rformance an Time 360° - 45° Rt (FIX) - 45° Ltt (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt - 45° Rt	hin. Control for V on v	Ces/gradie /iAil 3. Cruise. (I V <sub>max</sub> Vi Vi	nt Build-up). FUL H (FIX) Time for	FUEL Rud L DEFLECT Hi Ii 90°	
<ul> <li>4. Remari</li> <li>4. Remari</li> <li>4. Remari</li> <li>5. Trim Chang</li> <li>1. Contro</li> <li>2. Runaw</li> <li>5 sec d</li> <li>5 sec d</li> <li>5 sec d</li> <li>6. 45° Lft</li> <li>3. 45° Rt</li> <li>4. 60° Ø, 1</li> <li>5. 45° Lft</li> <li>6. 45° Rt</li> <li>7. 60° Ø, 1</li> <li>8. 45° Lft</li> <li>9. 45° Rt</li> <li>9. 45° Rt</li> <li>10. 45° Rt</li> <li>11. 45° Rt</li> <li>11. 45° Rt</li> <li>11. Rt Ø 10</li> <li>2. Lft 10°</li> <li>9. Phugoid (H</li> <li>Sidesilps, T</li> <li>1. Rt</li> <li>2. Lft</li> <li>4. Lft</li> </ul>	ks: ges: Hi ay Trim: Elev delay (build-up formance an Time 360° - 45° Rt (FIX) - 45° Rt (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt - 45° Rt - 45° Rt	V V On V On V	ces/gradie /iAil s. Cruise. (I V <sub>max</sub> Vi	nt Build-up). FUL H (FIX) Time for	FUEL Rud L DEFLECT Hi Ii 90°	
<ol> <li>4. Reman</li> <li>5. Trim Chang</li> <li>1. Contro</li> <li>2. Runaw</li> <li>5 sec d</li> <li>5 sec d</li> <li>5 sec d</li> <li>60° Ø, 1</li> <li>2. 45° Lft</li> <li>3. 45° Rt-</li> <li>4. 60° Ø, 1</li> <li>5. 45° Lft</li> <li>6. 45° Rt-</li> <li>7. 60° Ø, 1</li> <li>8. 45° Lft</li> <li>9. 45° Rt-</li> <li>9. 45° Rt-</li> <li>10. 45° Lft</li> <li>11. 45° Rt-</li> <li>11. 45° Rt-</li> <li>12. Lft 10°</li> <li>9. Phugoid (H</li> <li>Sideslips, T</li> <li>1. Rt</li> <li>2. Lft</li> <li>7. RIM (I</li> <li>3. Rt</li> <li>4. Lft</li> </ol>	rs: ges: Hi ay Trim: Elev delay (build-up rformance an Time 360° - 45° Rt (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt - 45° Rt - 45° Rt	on p) d Aileron Rolls Time for 90° Time for 90° Time for 90° Time for 90°	/iAil s. Cruise. (I V <sub>max</sub> Vi Vi	Build-up). FUL H	FUEL Rud L DEFLECT Hi Ii 90°	
<ol> <li>Trim Chang         <ol> <li>Contro</li> <li>Runaw</li> <li>5 sec d</li> <li>Turning Pei</li> <li>60° Ø, 1</li> <li>45° Kt</li> <li>45° Kt</li> <li>46° Ø, 1</li> <li>5. 45° Lft</li> <li>60° Ø, 1</li> <li>5. 45° Lft</li> <li>60° Ø, 1</li> <li>8. 45° Kt</li> <li>9. 45° Rt</li> <li>9. 45° Rt</li> <li>10. 45° Lft</li> <li>11. 45° Rt</li> <li>11. 45° Rt</li> <li>11. Rt Ø 10</li> <li>Lft 10°</li> <li>Phugoid (H</li> <li>Sideslips, T</li> <li>1. Rt</li> <li>Lft</li> <li>TRIM (I</li> <li>3. Rt</li> <li>Lft</li> </ol></li> </ol>	ges: Hi ay Trim: Elev delay (build-up formance an Time 360° - 45° Rt (FIX) - 45° Ltt (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt - 45° Rt	v p) d Aileron Rolls Time for 90° Time for 90° Time for 90° Time for 90° Time for 90°	/iAil s. Cruise. (I V <sub>max</sub> Vi Vi	Build-up). FUL H	Rud L DEFLECT _ Hi Ii 90°	
<ol> <li>Frim Chang         <ol> <li>Contro</li> <li>Runaw</li> <li>S sec d</li> <li>Turning Pei</li> <li>60° Ø, 1</li> <li>45° Lft</li> <li>45° Lft</li> <li>45° Lft</li> <li>60° Ø, 1</li> <li>5. 45° Lft</li> <li>60° Ø, 1</li> <li>5. 45° Lft</li> <li>9. 45° Rt-</li> <li>7. 60° Ø, 1</li> <li>8. 45° Lft</li> <li>9. 45° Rt-</li> <li>9. 45° Rt-</li> <li>10. 45° Lft</li> <li>11. 45° Rt-</li> <li>Spiral Stabi</li> <li>1. Rt Ø 10</li> <li>2. Lft 10°</li> <li>Phugoid (H</li> <li>Sideslips, T</li> <li>1. Rt</li> <li>2. Lft</li> <li>TRIM (I</li> <li>3. Rt</li> <li>4. Lft</li> </ol></li> </ol>	ges: HI ay Trim: Elev delay (build-up formance an Time 360° - 45° Rt (FIX) - 45° Lft (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt - 45° Rt	v p) d Aileron Rolls Time for 90° Time for 90° Time for 90° Time for 90° Time for 90°	Ail S. Cruise. (I V <sub>max</sub> Vi Vi	Build-up). FUL H		
1. Contro 2. Runaw 5 sec d 5 sec d 5. Turning Per 1. 60° Ø, 1 2. 45° Rt- 4. 60° Ø, 1 5. 45° Rt- 7. 60° Ø, 1 8. 45° Rt- 7. 60° Ø, 1 8. 45° Rt- POWER 10. 45° Lft 11. 45° Rt- POWER 10. 45° Lft 11. 45° Rt- DOWER 1. Rt Ø 10 2. Lft 10° 0. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft TRIM (f 3. Rt 4. Lft	ay Trim: Elev delay (build-up formance an Time 360° - 45° Rt (FIX) - 45° Lft (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt - 45° Rt	on	Ail 5. Cruise. (I V <sub>max</sub> Vi Vi	Build-up). FUL H	Rud L DEFLECT Hi Ii Ii	
2. Runaw 5 sec d 5 sec d 5. Turning Per 1. 60° Ø, 1 2. 45° Lft 3. 45° Rt- 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- POWER 10. 45° Lft 11. 45° Rt- POWER 10. 45° Lft 11. A5° Rt- B. Spiral Stabi 1. Rt Ø 10 2. Lft 10° 9. Phugoid (H 5. Sideslips, T 1. Rt TRIM (f 3. Rt 4. Lft	ay Trim: Elev Jelay (build-up fformance an Time 360° - 45° Rt (FIX) - 45° Ltt (FIX) Time 360° - 45° Rt (FIX) Time 360° - 45° Rt	p) d Aileron Rolls Time for 90° Time for 90° Time for 90° Time for 90° Time for 90°	Ail 5. Cruise. (I V <sub>max</sub> Vi Vi	Build-up). FUL H H (FIX) Time for	Rud L DEFLECT _ Hi Ii Ii 90°	
5 sec d 5. Turning Per 1. 60° Ø, 1 2. 45° Lft 3. 45° Rt - 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt - 7. 60° Ø, 1 8. 45° Rt - POWER 10. 45° Rt - POWER 11. 45° Rt - 11. 45° Rt - 11. 45° Rt - 12. Lft 10° 0. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft TRIM (f 3. Rt 4. Lft	telay (build-u) rformance an Fime 360° - 45° Rt (FIX) - 45° Ltt (FIX) - 45° Rt (FIX) - 45° Ltt (FIX) Fime 360° - 45° Rt - 45° Rt	p) d Aileron Rolls Time for 90° Time for 90° Time for 90° Time for 90° Time for 90°	S. Cruise. (I V <sub>max</sub> Vi Vi	Build-up). FUL H H (FIX) Time for	L DEFLECT _ Hi Ii Ii 90°	
<ol> <li>Turning Peression 1. 60° Ø, 1</li> <li>2. 45° Lft</li> <li>3. 45° Rt -</li> <li>4. 60° Ø, 1</li> <li>5. 45° Lft</li> <li>6. 45° Rt -</li> <li>7. 60° Ø, 1</li> <li>8. 45° Lft</li> <li>9. 45° Rt -</li> <li>POWEF</li> <li>10. 45° Lft</li> <li>11. 45° Rt -</li> <li>POWEF</li> <li>10. 45° Lft</li> <li>11. 45° Rt -</li> <li>POWEF</li> <li>10. 2. Lft 10°</li> <li>Phugoid (H</li> <li>Sideslips, T</li> <li>1. Rt</li> <li>2. Lft</li> <li>TRIM (f</li> <li>3. Rt</li> <li>4. Lft</li> </ol>	rformance an Fime 360° - 45° Rt (FIX) - 45° Ltt (FIX) Time 360° - 45° Rt (FIX) Fime 360° - 45° Rt - 45° Rt	d Aileron Rolls Time for 90° Time for 90° Time for 90° Time for 90° Time for 90°	s. Cruise. (I V <sub>max</sub> Vi Vi	Build-up). FUL H	L DEFLECT _ Hi Ii Ii 90°	
1. 60° Ø, 1 2. 45° Lft 3. 45° Rt - 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt - 7. 60° Ø, 1 8. 45° Lft 9. 45° Lft 9. 45° Lft 10. 45° Lft 11. 45° Rt - 10. 2. Lft 0° 2. Lft 10° 5. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft 7. RIM (f 3. Rt 4. Lft	Fime 360° - 45° Rt (FIX) - 45° Lft (FIX) Fime 360° - 45° Rt (FIX) - 45° Rt (FIX) Fime 360° - 45° Rt - 45° Rt (FIX)	Time for 90° Time for 90° Time for 90° Time for 90° Time for 90°	V <sub>max</sub> Vi Vi	H	_ Hi Ii Ii 90°	
2. 45° Lft 3. 45° Rt- 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- POWEF 10. 45° Lft 11. 45° Rt- 1. Rt Ø 10 2. Lft 10° 9. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft TRIM (f 3. Rt 4. Lft	- 45° Rt (FIX) - 45° Lft (FIX) Time 360° - 45° Rt (FIX) - 45° Lft (FIX) Time 360° - 45° Rt - 45° Rt	Time for 90° Time for 90° Time for 90° Time for 90° Time for 90°	Vi	H (FIX) Time for	I I 90°	
3. 45° Rt- 4. 60° Ø, 1 5. 45° Lft 6. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- 90 WEF 10. 45° Rt- 10. 45° Rt- 11. 45° Rt- 1. Rt Ø 10 2. Lft 10° 9. Phugoid (H 5. Sideslips, T 1. Rt 2. Lft 7. RIM (f 3. Rt 4. Lft	- 45° Lft (FIX) Time 360° - 45° Rt (FIX) - 45° Lft (FIX) Time 360° - 45° Rt - 45° Lft (FIX)	Time for 90° Time for 90° Time for 90° Time for 90°	Vi	H (FIX) Time for	li li 90°	
4. 60° Ø, 1 5. 45° Lft 6. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- 90 WEF 10. 45° Rt- 10. 45° Rt- 11. 45° Rt- 1. Rt Ø 10 2. Lft 10° 9. Phugoid (H . Sideslips, T 1. Rt 2. Lft 4. Lft	Fime 360° - 45° Rt (FIX) - 45° Lft (FIX) Fime 360° - 45° Rt - 45° I ft (FIX)	Time for 90° Time for 90° Time for 90°	Vi Vi	H (FIX) Time for	li /i / 90°	
5. 45° Lft 6. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- POWEF 10. 45° Rt- 10. 45° Rt- 11. 45° Rt- 1. Rt Ø 10 2. Lft 10° 9. Phugoid (H Sideslips, T 1. Rt 2. Lft 7. RIM (I 3. Rt 4. Lft	- 45° Rt (FIX) - 45° Lft (FIX) Time 360° - 45° Rt - 45° Lft (FIX)	Time for 90° Time for 90° Time for 90°	_ Vi	(FIX) Time for	li 90°	
6. 45° Rt- 7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- POWEF 10. 45° Rt- 11. 45° Rt- 1. Rt Ø 10 2. Lft 10° 9. Phugoid (H Sideslips, T 1. Rt 2. Lft TRIM (I 3. Rt 4. Lft	- 45° Lft (FIX) Time 360° - 45° Rt - 45° I ft (FIX)	Time for 90° Time for 90°	_ VI	(FIX) Time for	90°	
7. 60° Ø, 1 8. 45° Lft 9. 45° Rt- POWEF 10. 45° Rt- 11. 45° Rt- 1. Rt Ø 10 2. Lft 10° 5. Phugoid (H Sideslips, T 1. Rt 2. Lft TRIM (( 3. Rt 4. Lft	Time 360° - 45° Rt - 45° I # (E1Y)	Time for 90°_	_ Vi	(FIX) Time for	li · 90°	
8. 45° Lft 9. 45° Rt- POWEF 10. 45° Lft 11. 45° Rt- 1. Spiral Stabi 1. Rt Ø 10 2. Lft 10° 0. Phugoid (H . Sideslips, T 1. Rt 2. Lft TRIM (i 3. Rt 4. Lft	- 45° Rt	Time for 90°_		(FIX) Time for	90°	·····
9. 45° Rt- POWER 10. 45° Lft 11. 45° Rt- 1. Spiral Stabi 1. Rt Ø 10 2. Lft 10° 0. Phugoid (H . Sideslips, T 1. Rt 2. Lft TRIM (i 3. Rt 4. Lft	- 45° I # (FIY)	Time for 90°_				· · · · · · · · · · · · · · · · · · ·
POWER 10. 45° Lft 11. 45° Rt- 1. Spiral Stabi 1. Rt Ø 10 2. Lft 10° 0. Phugoid (H . Sideslips, T 1. Rt 2. Lft TRIM (i 3. Rt 4. Lft						
10. 45° Lft 11. 45° Rt- 1. Spiral Stabi 1. Rt Ø 10 2. Lft 10° 9. Phugoid (H . Sideslips, T 1. Rt 2. Lft TRIM (i 3. Rt 4. Lft	R APPROACH					
11. 45° Rt- 1. Spiral Stabi 1. Rt Ø 10 2. Lft 10° 9. Phugoid (H . Sideslips, T 1. Rt 2. Lft TRIM (i 3. Rt 4. Lft	– 45° Rt (FIX)	Time for 90° _		······································		
<ol> <li>Spiral Stabi 1. Rt Ø 10 2. Lft 10° Phugoid (H Sideslips, T 1. Rt 2. Lft TRIM (i 3. Rt 4. Lft</li> </ol>	- 45° Lft (FIX)	Time for 90°_				
1. Rt Ø 10 2. Lft 10° 9. Phugoid (H . Sideslips, T 1. Rt 2. Lft TRIM (i 3. Rt 4. Lft	ility PA Hi		_ Vi	P	wr	**************************************
2. Lft 10° 9. Phugoid (H 1. Sideslips, T 1. Rt 2. Lft TRIM (i 3. Rt 4. Lft	°	°/				
<ul> <li>Phugoid (H</li> <li>Sideslips, T</li> <li>1. Rt</li> <li>2. Lft</li> <li>TRIM (I</li> <li>3. Rt</li> <li>4. Lft</li> </ul>	***	°/		sec. (1/2 - 2).		
. Sideslips, T 1. Rt 2. Lft TRIM ( 3. Rt 4. Lft	i C <sub>1</sub> )					
1. Rt 2. Lft TRIM ( 3. Rt 4. Lft	RIŇ (L) HI					
2. Lft TRIM ( 3. Rt 4. Lft	°, Fr	Fa	Fs	dr	eb	de
TRIM ( 3. Rt 4. Lft	°, Fr	Fa	Fs	dr	da	00
3. Rt 4. Lft	CR) Hi	Vi	· • •		vu	00
4. Lft	°, Fr	Fa	Fs	dr	de	do
	°. Fr	Fa	Fs	dr	ua eh	00
5. D.E. wi	th rudder (Pic	ck up wina)		(,	va	ue
6. Remari	ks:				FUE	
					1 UEL	
italls, Gross W	Veiaht		יים	Trim		
. CR 1 0g TP						
	IMIVi	Mar				
. Remarket	IM VI IM Vi	Vw		Vs	Hi	
nemarka:	IM VI IM VI	Vw Vw		Vs Vs	Hi Hi	
0. 0. 1. 0- 7-	IM VI IM VI	Vw Vw		Vs Vs	Hi Hi	

٠

8.	Asymmetric Power - III		
	a. Climb configuration (MRP, Clim	b Vi, Trimmed-out)	
	NTC Feather	r No. 1	Eng. Rudder Free, 2 sec.
	Decel to 1.4 Vsl	kts. Ø and sid	eslip
	(Cond. permitting check 2 out c	on one side)	
	b. T.O. Configuration at V <sub>max</sub> Gear	and T.O. Flaps (168 kts.)	
	Fail 1 and 2 and decelerate hold	ding $\emptyset = ZERO$ .	
	Vi <sub>min</sub> Check	$0 = 5^{\circ}$ and SIDESLIP = ZE	RO.
	C. Al Min control speed fall 3 and	4, Fr Fa	······································
	Fs IRIM OU	I HANDS OFF AT 1, 2 VSI_	
	a. Remarks:		
9.	Boost OFF Operation Hi	Vi	Pwr
	a. Asymmetric Control 1 and 2 idle	e, 3 and 4 MRP	
	b. Response Fi	Fa	Fs
	c. Remarks:		
10.	Descent		
	a. CR Configuration Vi	· · · · · · · · · · · · · · · · · · ·	V/S
	1. Visibility	Attitud	de
	<ol><li>Engine operation at idle</li></ol>		
	3. Pressurization, systems, et	C	
	4. Remarks:		
	b. L Configuration Vi	v	//S
	1. Visibility	Attitud	de
	2. Engine operation at idle		
	3. Remarks:		
11.	Trim Changes Trim at Placard Spe	ed, PLF	
	a. riaps to 50% VI		-EF/111111   E/Trim
	a Elaps to 100% Vi	m P	DI E/Trim
	d Power to IDIS VI	== == Hi	Trim
	e Idle to HRP Vi	Δtt Τι	rim
	f GearliPVi	[//S Trim	1
	g. Flaps UP Vi	V/S Trir	n
	B		
12.	Asymmetric Power Go-around		
	a Out, Pa Vi	Hi	Pwr

13. General Comments Prior to Completion of Flying.

#### H. Approach and Landing

~ ~ ~ ~	noach and Landing			
1.	Pre-landing check:	Operating Weight		
	Alt Setting	Fuel Weight		
	W/V	Landing GR WT		
	Runway	Best Flare Speed		
	(Pilot Pwr and Steer	) Touchdown speed		
	(Copilot Allersons)	/S <sub>L</sub>		
2.	Traffic pattern:			
	a. Visibility	Control		
	b. Power response			
	c. Remarks:			
з.	Landing:			
	a. Flare	Response	Control	
	b. Float	Characteristics in groun	d effect	
	c. Touchdown	Nose-wheel off		Grd idle
	Reverse	Brakes	Steering	
	d. Directional contr	ol with ailerons		
	e. Stopping distanc	θ		
4.	Remarks:			
Post	-flight and Shut-dow	n		
1.	Normal procedures.	Ease and time to accomplish		
2.	Coordination			
2	Eucl			

.

1.

- 3. Fuel\_\_\_\_\_ 4. Flight Time\_\_\_\_\_ 5. Squawks\_
- J. Re-evaluate Cockpit and A/C in General



EXTERNAL INSPECTION	TOD START TOD FINISH
Remarks:	
1. Ease of Entry	Ladder
•	Steps
2. Location of Instruments and Controls	
3. Adjustment of Seat and Controls	
4. Comfort	
5. Ease of Identification of:	
Switches	
Controls	
Emergency Devices	
Warning Lights	
6. Egress – ground and Airborne	
BEFORE STARTING CHECKS	TOD
Remarks	
Complexity:	

.

STARTING ENGINES		Fuel	TOD	
Complexity:				
Ground Support:				
Equipment				
Personnel				
BEFORE TAXI CHECKS			TOD	
Estimated Break-out Force				
Longitudinal +	#	_#		
Lateral+#	#			
Directional+#	#	:		
Trim rate (Longitudinal) Aft		Sec		
For	e	Sec		
Flap Extension	Se	ec Retraction		Sec
TAXIING		Fuel	TOD	*********************
		RPM req to move	Ð	
Visibility				
Steering		N.W.S.		
		Brakes		
Visibility				
Power required	RPM, fuel/flow		pph	
Runway temp	°F. P.A		ft.	

TAKEOFF		Fuel_	4	#TOD	
Do brakes hold in MIL	PWR Yes	No			
Symmetry of brake rele	ase				
<b>Directional control</b>					
Rudder effective speed	I	k	nots		
Ease of rotation					
Lift-off speed		knots			
Estimated T/O distance	3	f	eet		
Gear up time	sec Flans	up time			SPC
Trim changes Landir	000 1 10p0	t			
Flane	.g.g.cu				
Are placards hard to excee Visibility during T/O an Adequacy of T/O trim s Speed stability during a	ed? Yes d Initial Climb etting: acceleration:	Νο			
CLIMB		Fuel_		#TOD	
<b>Control during climb</b>					
Longitudinal					
Directional					
Lateral					
Climb Schedule	5000 ft.	.891 <b>MN</b>	550		
	10000 ft.	.891MN	510		
	15000 ft.	.901MN	470		
	20000 ft.	.9051MN	430		
	25000 ft.	.910IMN	390		
	30000 ft.	.915IMN	360		
	35000 ft.	.921MN	320		
	39000 ft.	.921MN			

FIGURE

.

LEVEL OFF EASE Attitude Change	)			Fuel	°	#ТО	DD		
CRUISE	( Fuel	90% RPM		#		.861MI	N (recon	nmend	ed cruise)
Otart	1 461			**		10	U		l inear?
Sideslip:	Cfo	Hvy	Med	LI	t		Yes	No	Lindan
		Hvy	Med	Li	t		Yes	No	
Dutch Roll	Period				sec				
	Damping	Hvy	Med	Lt					
Cycles to Damp									
CRUISE cont.	39,000 ft.	.861MN							
<b>PIO Tendency</b>	Yes No	)							
Short Period	Cycles to D	amp							
	Period	<u></u>					sec		
Do controls h	nave dynamic	tendency	?						
			Yes	No					
Aileron Rolls:			ts	90					
				RL	-	Adv. Yaw			
1/2 deflection		_ sec		_ sec					
Full deflect.		sec		sec					
******	*****	***** D	AMPE	RS OF	F ******	********	******	******	*****
									Linear?
Sideslip:	$\mathbf{c}_{\ell_{oldsymbol{eta}}}$	Hvy	Med	Lt			Yes	No	
	$c_{n_{\beta}}$	Нvy	Med	Li			Yes	No	
Dutch Roll:	Period				sec	;			
	Damping	Ηνу	Med	Lt					
	Cycles to	Damp							
PIO Tendency	Yes No	)							
Short Period:	Cycles to D	amp							
	Period						sec		

FIGURE 3. TYPICAL FIGHTER AIRCRAFT QUALITATIVE EVALUATION FLIGHT CARDS (2 hour flight) (CONTINUED)

J

Finish:	Fu	el	#			TOD		
Speed brake	trim change	Hvv	Med	Lt		100		
	Extend	Push	Pull					
	Retract	Push	Pull					
MANEUVERING FI	LIGHT			IMN			20.	25 000 4
Fuel	#		.0				29.	35,000 ft.
Initial buffet			a					
Heavy buffet	***************************************		9 0 D				-	
Stick force	Hvv Med	1+	9 "max	•			g	
Linear	Yes No							
*********	****	******	******	*******	******	********		
ACCELEBATION T	012 IMN at 3	5 000 # /++	im 0 114	M				*********
Start:	Fuel	5,000 n. (n		•)		700		
NR Light1		~ P	#					
NB Trim Chan	38	t n		sec				
Stick force grad	99	# Pusn	Pull					
Finish fuel		·····						
******		<del>,</del>		*****		TOD		
CRUISE 1 15 IMM				*******	*******	************	*******	*******
Stort	<b>E</b> trad							35,000 ft.
Start	ruei_		#			TOD		
Sideolini	•	11						Linear?
Sidesiip:		HVY N	led	Lt		Yes	No	
Dutch Dutt	C <sub>n</sub> <sub>β</sub>	Hvy N	led	Lt		Yes	No	
Dutch Roll:	Period	· · · · · · · · · · · · · · · · · · ·		s	Bec			
	Damping	Hvy M ∽	led Lt					
	Cycles to	Damp						
PIO Tendency	Yes No							





*****	•,•••• =	amp					
*********	Period						
	**********	*******	DAMPE	RS OFF	*******	************	*********
							Linear?
Sideslip:	$c_{\ell_{eta}}$	Hvy	Med	Lt		Yes	No
	C <sub>n</sub> <sup>p</sup>	Нνу	Med	Lt		Yes	Νο
Dutch Roll:	Period				Sec		
	Damping	Нуу	Med	Lt			
	Cycles to	Damp_					
<b>PIO Tendency</b>	Yes No	)					
Short Period:	Cycles to D	)amp					
	Period						
******	*******	******	* DAMPE	RS ON	*******	******	*************
ileron Rolls:			t	90			Adverse Yaw
			R	L			
1/2 deflection			8ec		80C		
Full deflect.		8	30C	t	Bec		
Finish: Fuel						TOD	

٠



.

DECELERATIO	N TO 210 knots	30,000 ft.	(Long S	tat)				
Stick Force	gradient							
******	******	******	******	*******	*******	******	******	********
CRUISE	210 knots	30,0	000 ft.					
Start:	Fu	el	#	ŧ		TOD		
								Linear?
Sideslips:	$c_{\ell_{eta}}$	Hvy	Med	Lt		Yes	No	
	C <sub>n</sub> <sub>β</sub>	Hvy	Med	Lt		Yes	No	
Dutch Rolls	: Perioc	I			Sec			
	Damp	ing Hvy	/ Med	Lt				
	Cycles	s to Damp			_			
PIO Tenden	cy Yes M	No						
Short Period	ds: Cycles t	o Damp						
	Period_				· · · · · · · · · · · · · · · · · · ·	Se	с	
*****	******	*****	DAMPEF	RS OFF *	*******	*****	******	*******
								Linear?
Sideslips:	$c_{\ell_{eta}}$	Hvy	Med	Lt		Yes	No	
	$C_{n_{\beta}}$	Hvy	Med	Lt		Yes	No	
CRUISE	210 knots at 30	,000 ft.						
<b>Dutch Roll:</b>	Period.				_ Sec			
	Dampir	ng Hvy	Med	Lt				
	Cycles	to Damp_			-			
PIO Tenden	cy Yes I	vio 🛛						
Short Perio	ds: Cycles t	o Damp						
	Period_					Se	c	
Finish: Fue	I	#				TOD		

*******	*****	********* DAM	PERS ON *******	*****	*****
AILERON ROLLS	S		t90		Adverse Yaw
½ deflecti	on <b>R</b>	sec	L se	C	
Full defle	ct. R	sec	L se	C	
*****	******	*****	****	*****	*****
MANEUVERING	FLIGHT at 210 H	nots			
Fuel					
Initial Buffet		g Heavy B	uffet	q	
"max"		g			
Stick force g	radient: Hvy	Med Lt			
*****	*****	******	*****	*****	*****
STALLS Cru	ise Configuratio	n 25,000 ft.			
Fuel	#				
Cr Vw_		knots		Vs	knots
GLIDE Vw_		knots		Vs	knots
Remarks					
POWER APPROA	CH CONFIGURA	TION			
Gear extensio	on	sec			
Flap extensio	n	sec			
Asymmetric p	ower at 155 kno	ts			
MIL RWR Rug	lder Force	lvy Med L	_t		
MAX TWR Ru	dder Force	Hvy Med	Lt		
Trimability	MIL		МАХ	(	
STALLS:	Fuel	······································			
Vw	knots	Vs	kno	ts	
Remarks:					

.

#### Trim at 160 knots

							Liı	near?
Sideslip:	$c_{\ell_{\mathcal{R}}}$	Hvy	Med	Lt		Yes	No	
	C <sub>n</sub> <sup>µ</sup>	Ηνу	Med	Lt		Yes	No	
Dutch Roll:	Period_				_ sec			
	Damping	i Hvy	Med	Lt				
	Cycles to	Damp_			_			
<b>PIO Tendency</b>	Yes No	<b>b</b>						
Short Period:	Cycles to I	Damp			- 1/8			
	Period					sec	;	
****	*****	*******	DAMPE	RS OFF *	******	*****	*****	*****
Dutch Roll:	Period_				sec			
	Damping	Dam	ping	Hvy N	led Lt			
	Cycles to	Damp_						
<b>PIO Tendency</b>	Yes No	<b>b</b>						
Short Period:	Cycles to I	Damp						
	Period					sec	:	
******	*****	******	DAMPE	RS ON *	*****	******	*****	*****
AILERON ROLLS				t90			Adverse	ə Yaw
1/2 deflection	R		sec L		sec			
Full deflect	R		sec L		sec			
*****	******	********	*******	******	*****	******	******	*****
ACROBATICS								
Loop								
Immelman								
Barrel Roll								



INSTRUMENTS			
Holding at 20,000 ft.	250 knots	90-92%	
Penetration S/B	270 knots	90%	
Initial Clean	220 knots	94%	
Low Cone gear, 86%, flaps, 155 knots LANDING			
Normal traffic pattern 60% flaps			
Single engine go-around closed pattern			
Full stop Full flaps			
the second			
Touchdown speed knot	s' marker		
Touchdown speed knot	s' marker	*****	******
Touchdown speed knot	s' marker	#TOD	*****
Touchdown speed knot TAXIING Engine acceleration Idle to mil	s' marker Fuel sec	#TOD	*****
Touchdown speed knot TAXIING Engine acceleration Idle to mil Turning radius feet	s' marker Fuel sec	#TOD	*****
Touchdown speed knot TAXIING Engine acceleration Idle to mil Turning radius feet Re-evaluate cockpits	s' marker Fuel sec	#TOD	****
Touchdown speed knot TAXIING Engine acceleration Idle to mil Turning radius feet Re-evaluate cockpits ENGINE SHUTDOWN	s' marker Fuel sec	#TOD	*****
Touchdown speed knot TAXIING Engine acceleration Idle to mil Turning radius feet Re-evaluate cockpits ENGINE SHUTDOWN Check servicing for turn-around	s' marker Fuel sec	#TOD	*****
Touchdown speed knot TAXIING Engine acceleration Idle to mil Turning radius feet Re-evaluate cockpits ENGINE SHUTDOWN Check servicing for turn-around Time	s' marker Fuel sec	#TOD	*****
Touchdown speed knot TAXIING Engine acceleration Idle to mil Turning radius feet Re-evaluate cockpits ENGINE SHUTDOWN Check servicing for turn-around Time Oil qts	Fuel	#TOD	*****
Touchdown speed knot TAXIING Engine acceleration Idle to mil Turning radius feet Re-evaluate cockpits ENGINE SHUTDOWN Check servicing for turn-around Time Oil qts Hydraulic fluid qts	s' marker Fuel sec	#TOD	*****

TOD				beside A/C
START	Procedure			
F Flow RPM		_ F Flov	N	
Before Taxi Check				
TOD	_			
TAXI				
Power to Roll	Brakes	S	NS	
Nosewheel steering Turn Rad.				
NWS Off Brake turn				
Canopy Operation				
Visibility				
тор				
LINE UP				
Brakes Mil Pwr				
Pump one brake				
Engine Acc Time				~
RPMEGT		FF		
Throttle friction S NS				
FUEL L R				
TOD				

.

TAKEOFF					
Brake release					
A/B light					
NWS rel at Rudder Ef	f A/S				
CONTROL FORCES	LM	Н	lbs		
NW LIFT OFF					
T.O. ROLL		ft A/	S		
GEAR UP	sec.	FLAPS UP		sec	
Trim Changes	<u></u>				
Noises					
Press. Sys					
Acceleration	Rotation				
CLIMB					
Schedule	.9 to 35M				
Control					
Trim					
Visibility					
Dampers					
35M Time_			Fuel L	R	
	Th	rottle Mil	Level Off		
TOD					

٠

DAMPERS	PULSE	CYCLE	TIME
ON	Elev		
	Rud		
OFF	Elev		
	Rud		
"g"			
R	<u>_,_,_</u>		
	DAMPERS ON OFF "g" R	DAMPERS PULSE ON Elev Rud OFF Elev Rud	DAMPERS PULSE CYCLE ON Elev Rud OFF Elev Rud "'g"

.

Ľ

•

TURNING PERFORMANCE		300 Kts_		sec
Zoom to Slow	A/C			
PWR STALL	WARN		STALL	
230 Kts. Flight	Roll			
STABILITY				
	DAMPERS	PULSE	CYCLE	TIME
	ON	Elev		
		Rud		
	OFF	Elev		
		Rud		
	Sideslip	6° Approx.		
CUT ONE ENGIN	E			
EMERGENCY	GEAR EXTENSION	S	ec	
AIRSTART				
170 knots	Flaps Down			
Aileron Pov	wer			
Cycle gear		Flaps up		TRIM
FUEL	L		R	,
TOD				

DIVE 450 K	ts 12M	
CLOVERLEAF		
BARREL ROLL		
IMMELMAN		
Level at 20M	l inbound to VOR	
200 Kts	F FLOW	
250 Kts	F FLOW	
300 Kts	F FLOW	
HIGH CONE		
240 Kts.	Gear Flaps	Dive Brakes
1 g stall		
200 Kts.		
	STABILITY Check	
STALL RIGHT	TURN 190 Kts	
Clean up A/C	275 Kts. turn to ILS	
	Speed Brakes	Decelerate
350 Kts.	opeee Branco	Decentrate

£

SINGLE ENGINE GO-AROUND

#### SINGLE ENGINE TOUCH AND GO

RE-ENTER PITCH OUT

**NO FLAP LANDING** 

a.

**TRIM CHANGES** 

TAXI

.

#### AFTER LANDING CHECK

SHUTDOWN